## Numerical Analysis: Final exam

(50 marks, only the 5 best questions count)

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Question 1 (Floating point arithmetic, 10 marks). True or false? +1/-1

**1.** Let  $(\bullet)_3$  denote base 3 representation. It holds that

$$(120)_3 + (111)_3 = (1001)_3.$$

**2.** Let  $(\bullet)_2$  denote binary representation. It holds that

$$(1000)_2 \times (0.1\overline{01})_2 = (101.\overline{01})_2.$$

- 3. In Julia, Float64(.25) == Float32(.25) evaluates to true.
- 4. The spacing (in absolute value) between successive double-precision (Float64) floating point numbers is constant.
- 5. The machine epsilon is the smallest strictly positive number that can be represented in a floating point format.
- **6.** Let  $\mathbf{F}_{64} \subset \mathbf{R}$  denote the set of double-precision floating point numbers. If  $x \in \mathbf{F}_{64}$ , then x admits a finite decimal representation.
- 7. Let x be a real number. If  $x \in \mathbf{F}_{64}$ , then  $2x \in \mathbf{F}_{64}$ .
- 8. The following equality holds

$$(0.\overline{101})_2 = \frac{7}{3}.$$

- 9. In Julia, 256.0 + 2.0\*eps(Float64) == 256.0 evaluates to true.
- 10. The set  $\mathbf{F}_{64}$  of double-precision floating point numbers contains twice as many real numbers as the set  $\mathbf{F}_{32}$  of single-precision floating point numbers.
- 11. Let x and y be two numbers in  $\mathbf{F}_{64}$ . The result of the machine addition x + y is sometimes exact and sometimes not, depending on the values of x and y.

Question 2 (Iterative method for linear systems, 10 marks). Assume that  $A \in \mathbb{R}^{n \times n}$  is a nonsingular matrix and that  $b \in \mathbb{R}^n$ . We wish to solve the linear system

$$\mathbf{A}\boldsymbol{x} = \boldsymbol{b} \tag{1}$$

using an iterative method where each iteration is of the form

$$\mathsf{M}\boldsymbol{x}_{k+1} = \mathsf{N}\boldsymbol{x}_k + \boldsymbol{b}_k$$

Here A = M - N is a splitting of A such that M is nonsingular, and  $x_k \in \mathbb{R}^n$  denotes the k-th iterate of the numerical scheme.

1. (3 marks) Let  $e_k := x_k - x_*$ , where  $x_*$  is the exact solution to (1). Prove that

$$\boldsymbol{e}_{k+1} = \mathsf{M}^{-1} \mathsf{N} \boldsymbol{e}_k.$$

**2.** (3 marks) Let  $L = \|\mathsf{M}^{-1}\mathsf{N}\|_{\infty}$ . Prove that

$$\forall k \in \mathbf{N}, \qquad \|\boldsymbol{e}_k\|_{\infty} \leq L^k \|\boldsymbol{e}_0\|_{\infty}.$$

- **3.** (1 mark) Is the condition  $\|\mathsf{M}^{-1}\mathsf{N}\|_{\infty} < 1$  necessary for convergence when  $x_0 \neq x_*$ ?
- 4. (3 marks) Assume that A is strictly row diagonally dominant, in the sense that

$$\forall i \in \{1, \dots, n\}, \qquad |a_{ii}| > \sum_{j=1, j \neq i}^{n} |a_{ij}|.$$

Show that, in this case, the inequality  $\|M^{-1}N\|_{\infty} < 1$  holds for the Jacobi method, i.e. when M contains just the diagonal of A. You may take for granted the following expression for the  $\infty$ -norm of a matrix  $X \in \mathbf{R}^{n \times n}$ :

$$\|\mathsf{X}\|_{\infty} = \max_{1 \le i \le n} \sum_{j=1}^{n} |x_{ij}|.$$

5. (Bonus +1) Write down a few iterations of the Jacobi method when

$$\mathsf{A} = \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix}, \qquad \boldsymbol{b} \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \qquad \boldsymbol{x}_0 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}.$$

Is the method convergent?

Question 3 (Nonlinear equations, 10 marks). Assume that  $x_* \in \mathbf{R}^n$  is a solution to the equation

$$\boldsymbol{F}(\boldsymbol{x}) = \boldsymbol{x},$$

where  $F \colon \mathbf{R}^n \to \mathbf{R}^n$  is a smooth nonlinear function. We consider the following fixed-point iterative method for approximating  $\mathbf{x}_*$ :

$$\boldsymbol{x}_{k+1} = \boldsymbol{F}(\boldsymbol{x}_k). \tag{2}$$

1. (8 marks) Assume in this part that F satisfies the local Lipschitz condition

$$\forall \boldsymbol{x} \in B_{\delta}(\boldsymbol{x}_*), \qquad \|\boldsymbol{F}(\boldsymbol{x}) - \boldsymbol{F}(\boldsymbol{x}_*)\| \le L \|\boldsymbol{x} - \boldsymbol{x}_*\|, \tag{3}$$

with  $0 \leq L < 1$  and  $\delta > 0$ . Here  $B_{\delta}(\boldsymbol{x}_*)$  denotes the open ball of radius  $\delta$  centered at  $\boldsymbol{x}_*$ . Show that the following statements hold:

- (2 marks) There is no fixed point of F in  $B_{\delta}(x_*)$  other than  $x_*$ .
- (2 marks) If  $x_0 \in B_{\delta}(x_*)$ , then all the iterates  $(x_k)_{k \in \mathbb{N}}$  belong to  $B_{\delta}(x_*)$ .
- (3 marks) If  $x_0 \in B_{\delta}(x_*)$ , then the sequence  $(x_k)_{k \in \mathbb{N}}$  converges to  $x_*$  and

$$orall k \in \mathbf{N}, \qquad \|oldsymbol{x}_k - oldsymbol{x}_*\| \leq L^k \|oldsymbol{x}_0 - oldsymbol{x}_*\|.$$

2. (3 marks) Explain with an example how the iterative scheme (2) can be employed for solving a nonlinear equation of the form

$$\boldsymbol{f}(\boldsymbol{x}) = \boldsymbol{0}.$$

**3.** (Bonus +1) Let  $J_F: \mathbb{R}^n \to \mathbb{R}^{n \times n}$  denote the Jacobian matrix of F. Show that if

$$\forall \boldsymbol{x} \in B_{\delta}(\boldsymbol{x}_*), \qquad \|\mathbf{J}_F(\boldsymbol{x})\| \leq L,$$

then the local Lipschitz condition (3) is satisfied.

Question 4 (Error estimate for eigenvalue problem, 10 marks). Let  $\|\bullet\|$  denote the Euclidean norm, and assume that  $A \in \mathbb{R}^{n \times n}$  is symmetric and nonsingular.

- **1.** (**5 marks**) Describe with words and pseudocode a simple numerical method for calculating the eigenvalue of A of smallest modulus, as well as the corresponding eigenvector.
- **2.** (1 mark) Let  $M \in \mathbb{R}^{n \times n}$  denote a nonsingular symmetric matrix. Prove that

$$\forall \boldsymbol{x} \in \mathbf{R}^n, \qquad \|\mathsf{M}\boldsymbol{x}\| \ge \|\mathsf{M}^{-1}\|^{-1}\|\boldsymbol{x}\|.$$
(4)

Let  $\lambda_{\min}(M)$  denote the eigenvalue of M of smallest modulus. Deduce from (4) that

$$\forall \boldsymbol{x} \in \mathbf{R}^n, \qquad \|\mathsf{M}\boldsymbol{x}\| \ge |\lambda_{\min}(\mathsf{M})| \|\boldsymbol{x}\|. \tag{5}$$

**3.** (4 marks) Assume that  $\widehat{\lambda} \in \mathbf{R}$  and  $\widehat{v} \in \mathbf{R}^n$  are such that

$$\|\mathbf{A}\widehat{\boldsymbol{v}} - \widehat{\lambda}\widehat{\boldsymbol{v}}\| = \varepsilon > 0, \qquad \|\widehat{\boldsymbol{v}}\| = 1.$$
(6)

Using (5), prove that there exists an eigenvalue  $\lambda$  of A such that

$$|\lambda - \widehat{\lambda}| \le \varepsilon.$$

4. (Bonus +1) Show that, in the more general case where  $A = VDV^{-1}$  is diagonalizable but not necessarily Hermitian, equation (6) implies the existence of an eigenvalue  $\lambda$ of A with

$$|\widehat{\lambda} - \lambda| \le \|\mathsf{V}\| \|\mathsf{V}^{-1}\| \varepsilon.$$

**Hint**: Introduce  $\boldsymbol{r} = A\widehat{\boldsymbol{v}} - \widehat{\lambda}\widehat{\boldsymbol{v}}$  and rewrite

$$\|\widehat{\boldsymbol{v}}\| = \|(\mathsf{A} - \widehat{\lambda}\mathsf{I})^{-1}\boldsymbol{r}\| = \|\mathsf{V}(\mathsf{D} - \widehat{\lambda}\mathsf{I})^{-1}\mathsf{V}^{-1}\boldsymbol{r}\|.$$

Question 5 (Interpolation error, 10 marks). Let u denote the function

$$u\colon [0,2\pi] \to \mathbf{R};$$
$$x \mapsto \cos(x).$$

Let  $p_n \colon [0, 2\pi] \to \mathbf{R}$  denote the interpolating polynomial of u through at the nodes

$$x_i = \frac{2\pi i}{n}, \qquad i = 0, \dots, n$$

- **1.** (3 marks) Using a method of your choice, calculate  $p_n$  for n = 2.
- **2.** (6 marks) Let  $n \in \mathbb{N}_{>0}$  and  $e_n(x) := u(x) p_n(x)$ . Prove that

$$\forall x \in [0, 2\pi], \qquad |e_n(x)| \le \frac{|\omega(x)|}{(n+1)!},$$

where we introduced

$$\omega_n(x) := \prod_{i=0}^n (x - x_i).$$

Hint: You may find it useful to introduce the function

$$g(t) = e_n(t)\omega_n(x) - e_n(x)\omega_n(t).$$

**3.** (1 mark) Does the maximum absolute error

$$E_n := \sup_{x \in [0,2\pi]} |e_n(x)|$$

tend to zero in the limit as  $n \to \infty$ ?

(Bonus + 1) Using the Gregory–Newton formula, find a closed expression for the sum

$$S(n) = \sum_{k=1}^{n} k^2.$$

**Question 6** (Numerical integration, **10 marks**). The third exercise below is independent of the first two.

1. (5 marks) Construct an integration rule of the form

$$\int_{-1}^{1} u(x) \, \mathrm{d}x \approx w_1 u\left(-\frac{1}{2}\right) + w_2 u(0) + w_3 u\left(\frac{1}{2}\right)$$

with a degree of precision equal to at least 2.

- 2. (1 mark) What is the degree of precision of the rule constructed?
- **3.** (4 marks) The Gauss–Laguerre quadrature rule with *n* nodes is an approximation of the form

$$\int_0^\infty u(x) e^{-x} dx \approx \sum_{i=1}^n w_i u(x_i),$$

such that the rule is exact when u is a polynomial of degree less than or equal to 2n-1. Find the Gauss–Laguerre rule with one node (n = 1).

4. (Bonus +1) Find the Gauss-Laguerre quadrature rule with two nodes (n = 2). You may find it useful to first calculate the Laguerre polynomial of degree 2.